

Review

- Objects
- Classes
- Objects and Arrays

Models of Motion with Objects

- Linear Translation
- Bouncing
- Rotation
- Seeking a Target
- Gravity and Friction
- Accelerating toward a Target
- Perspective (starfield)

Components of the Main Sketch

1. A global array to hold all objects
2. A loop to update and draw all objects, if they exist
3. A global counter to track next available array index
4. A function to create and store new objects

Outline for a Graphic Object Class

1. All fields necessary to maintain object state
 - Variables for (x, y) position at a minimum
2. A constructor to initialize new objects
3. A step() method to update state of the object
 - Including object location, and any other fields desired
4. A draw() method to render object on sketch

```
// A simple Box class
class Box {
    float x, y;

    Box(float tx, float ty) {
        x = tx;    // x position
        y = ty;    // y position
    }

    void step() {}

    void draw() {
        fill(200);
        rect(x, y, 20, 20);
    }
}
```

BoxMaker.pde

Linear Translation

```
class Mover {
    float x, y, vx, vy;

    Mover(float tx, float ty) {
        x = tx;    // x position
        y = ty;    // y position
        vx = 1.0; // x velocity
        vy = 0.0; // y velocity
    }

    void step() {
        x = x + vx; // Motion
    }
}
```

How can we make the box bounce off the walls?

BoxMover.pde

Rotation

```

class Rotator {
    float x, y;
    float angle;

    Rotator(float tx, float ty) {
        x = tx; // x position
        y = ty; // y position
        angle = 0.0;
    }

    void step() {
        angle = angle + radians(5);
    }

    void draw() {
        fill(200);
        pushMatrix();
        translate(x, y);
        rotate(angle);
        rect(0, 0, 20, 20);
        popMatrix();
    }
}

```

How can we make the box orbit instead of rotate?

BoxRotator.pde

Gravity

```

class Dropper {
    float x, y, vx, vy, ay;

    Dropper(float tx, float ty) {
        x = tx; // x position
        y = ty; // y position
        vx = 0.0; // x velocity
        vy = 0.0; // y velocity
        ay = 0.02; // gravity
    }

    void step() {
        if (y <= height) { // Stop at the floor
            x = x + vx; // Equations of motion
            y = y + vy;
            vy = vy + ay;
        }
    }
}

```

BoxDropper.pde

Drift Toward a Target

```

class Drifter {
    float x, y, vx, vy;
    float ax, ay;
    float targetx, targety;

    Drifter(float tx, float ty) {
        x = tx; // x position
        y = ty; // y position
        vx = 0.0; // x velocity
        vy = 0.0; // y velocity
        ax = 0.0; // x acceleration
        ay = 0.0; // y acceleration

        // Initialize a random target
        targetx = random(width);
        targety = random(height);
    }

    ...
}

```

Box is accelerated toward the target

BoxDrifter.pde

Seeking a Target

```

class Seeker {
    float x, y;
    float targetx, targety;

    Seeker(float tx, float ty) {
        x = tx; // x position
        y = ty; // y position
        targetx = random(width); // Initial target
        targety = random(height); // location
    }

    void step() {

        x = x + 0.01*(targetx - x); // New position is
        y = y + 0.01*(targety - y); // toward target

        if (dist(x, y, targetx, targety) < 40.0) {
            targetx = random(width); // Change target
            targety = random(height); // when too close
        }
    }
}

```

How can we visualize the target?

BoxSeeker.pde

Gravity and Friction (and Bounce)

```

class Bouncer {

    ...

    void step() {
        x = x + vx; // Equations of motion
        y = y + vy;
        vy = vy + ay;

        if (y >= height) { // Bounce off the floor
            y = height; // Prevent box catch at floor
            vy = -0.7*vy; // Bounce with friction
        }
    }

    ...
}

```

BoxBouncer.pde

Drift Toward a Target (Cont'd)

```

void step() {

    ax = 0.0002*(targetx-x); // Accelerate toward target
    ay = 0.0002*(targety-y);

    vy = vy + ay; // Update velocity
    vx = vx + ax; // Constrain velocity
    vx = constrain(vx, -0.5, 0.5);
    vy = constrain(vy, -0.5, 0.5);

    x = x + vx; // Update position
    y = y + vy;

    // Calculate new target when too close
    if (dist(x, y, targetx, targety) < 40.0) {
        targetx = random(width);
        targety = random(height);
    }
}

```

BoxDrifter.pde

AllBoxes

```
// AllBoxes
Box aBox;
Mover aMover;
Rotator aRotator;
Seeker aSeeker;
Dropper aDropper;
Bouncer aBouncer;
Drifter aDrifter;

void setup() {
    size(500, 500);
    rectMode(CENTER);

    aBox = new Box( random(width), random(0.5*height) );
    aMover = new Mover( random(width), random(0.5*height) );
    aRotator = new Rotator( random(width), random(0.5*height) );
    aSeeker = new Seeker( random(width), random(0.5*height) );
    aDropper = new Dropper( random(width), random(0.5*height) );
    aBouncer = new Bouncer( random(width), random(0.5*height) );
    aDrifter = new Drifter( random(width), random(0.5*height) );
}

void draw() {
    background(0);

    // Update all box objects
    aBox.step();
    aMover.step();
    aRotator.step();
    aSeeker.step();
    aDropper.step();
    aBouncer.step();
    aDrifter.step();

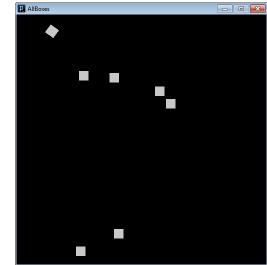
    // Draw all boxes
    aBox.draw();
    aMover.draw();
    aRotator.draw();
    aSeeker.draw();
    aDropper.draw();
    aBouncer.draw();
    aDrifter.draw();
}
```

AllBoxes.pde

AllBoxes

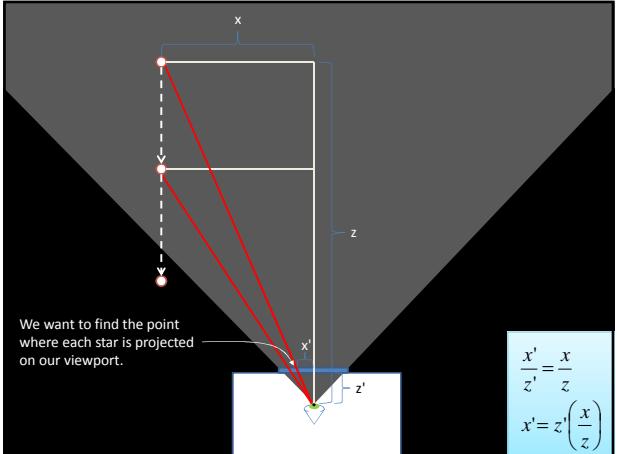
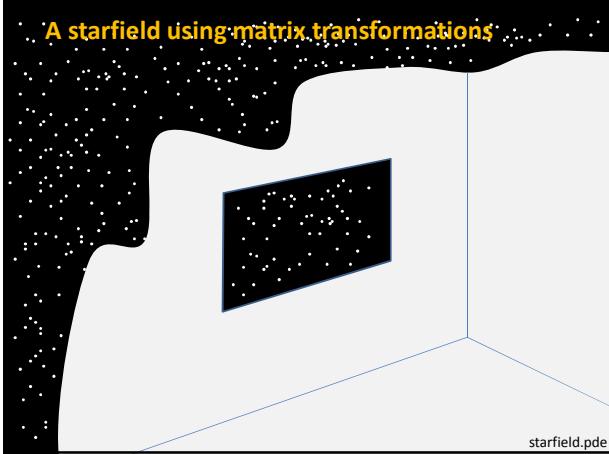
- Note

- We changed the x-y position and rotation.
- Other field values can be changed instead, such as fill color, scale, width, height, ...
- The main program never changed.
- Each object encapsulates its own behavior, so all can coexist.



AllBoxes.pde

A starfield using matrix transformations



Star Class

```
class Star {
    // Star coordinates in 3D
    float x;
    float y;
    float z;

    Star() {
        x = random(-5000, 5000);
        y = random(-5000, 5000);
        z = random(0, 2000);
    }

    void update() {
        // Move star closer to viewport
        z -= 10;

        // Reset star if it passes viewport
        if (z <= 0.0) {
            reset();
        }
    }

    void draw() {
        // Project star only viewport
        float offsetX = 100.0*(x/z);
        float offsetY = 100.0*(y/z);
        float scaleZ = 0.0001*(2000.0-z);

        // Draw this star
        pushMatrix();
        translate(offsetX, offsetY);
        scale(scaleZ);
        ellipse(0, 0, 20, 20);
        popMatrix();
    }
}
```

starfield

```
// starfield

// Array of stars
Star[] stars = new Star[400];

void setup() {
    size(600, 600);
    smooth();
    stroke(255);
    strokeWeight(5);
    rectMode(CENTER);

    // Init all stars
    for (int i=0; i<stars.length; i++) {
        stars[i] = new Star();
    }
}

void draw() {
    background(0);

    // Draw all stars wrt center of screen
    translate(0.5*width, 0.5*height);

    // Update and draw all stars
    for (int i=0; i<stars.length; i++) {
        stars[i].update();
        stars[i].draw();
    }
}
```