These questions relate to lecture material and aim to highlight the most important concepts. We will cover questions similar to these for our midterm

1. Frame 1 is rotated 30 degrees around the $Z$ axis from frame 0 . What $3 \times 3$ rotation matrix corresponds to this rotation? Draw frame 1 and frame 0.
2. Frame 1 is rotated 30 degrees around the $Z$ axis and translated ( $1,4,6$ ) units from frame 0 . What is the $4 \times 4$ transformation matrix which converts from frame 1 to frame 0 ? Draw frame 1 and frame 0 .
3. Consider frame 1 from the previous question. What is the coordinate of the origin of frame 1 with respect to frame 0 ?
4. Again, consider frame 1 from question 2. What is the coordinate of $(1,0,0)$ in frame 1 with respect to frame 0?
5. Again using frame 0 and frame 1 from question 2 . What is the coordinate of the point $(0,0,0)$ in frame 0 with respect to frame 1?
